

Matrix Form of the Equations

N ORDER TO FACILITATE the mathematical formulation of the methods that we will examine in this course, it is very useful to express the space-time kinetics equations in matrix form. This makes them look independent of any particular

energy group, and produces a much more compact notation. To do this we have to introduce the following vectors and matrices:

• A diagonal matrix of the velocities

$$\begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \\ \mathbf{v}_G \end{bmatrix}$$

• A column vector of the fluxes,

$$\begin{bmatrix} \phi \end{bmatrix} = \begin{bmatrix} \phi_1 \\ \phi_2 \\ \vdots \\ \phi_G \end{bmatrix}$$

• A column vector of the net currents,

$$\begin{bmatrix} \overrightarrow{J} \\ \overrightarrow{J} \end{bmatrix} = \begin{vmatrix} \overrightarrow{J}_1 \\ \overrightarrow{J}_2 \\ \vdots \\ \overrightarrow{J}_G \end{vmatrix}$$

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• A square matrix of the cross-sections,

$$\begin{bmatrix} \Sigma \end{bmatrix} = \begin{bmatrix} \Sigma_{t1} - \Sigma_{s1 \leftarrow 1} & -\Sigma_{s1 \leftarrow 2} & \dots & -\Sigma_{s1 \leftarrow G} \\ -\Sigma_{s2 \leftarrow 1} & \Sigma_{t2} - \Sigma_{s2 \leftarrow 2} & \dots & -\Sigma_{s2 \leftarrow G} \\ \vdots & \vdots & \vdots & \vdots \\ -\Sigma_{sG \leftarrow 1} & -\Sigma_{sG \leftarrow 2} & \dots & \Sigma_{tG} - \Sigma_{sG \leftarrow G} \end{bmatrix}$$
(EQ 19)

• A column vector of the prompt energy spectrum,

$$\begin{bmatrix} \chi^{\mathbf{p}} \end{bmatrix} = \begin{bmatrix} \chi_1^{\mathbf{p}} \\ \chi_2^{\mathbf{p}} \\ \vdots \\ \chi_{\mathbf{p}}^{\mathbf{p}} \end{bmatrix}$$

• A column vector of ν times the fission cross-section,

$$\begin{bmatrix} v \Sigma_{f} \end{bmatrix} = \begin{bmatrix} v \Sigma_{f1} \\ v \Sigma_{f2} \\ \vdots \\ v \Sigma_{fG} \end{bmatrix}$$

• D column vectors of the delayed neutron spectra,

$$\begin{bmatrix} \chi_{i}^{d} \end{bmatrix} = \begin{bmatrix} \chi_{i1}^{d} \\ \chi_{i2}^{d} \\ \vdots \\ \chi_{iG}^{d} \end{bmatrix}$$

• A diagonal matrix of the diffusion coefficients,

$$\begin{bmatrix} \mathbf{D} \end{bmatrix} = \begin{bmatrix} \mathbf{D}_1 \\ \mathbf{D}_2 \\ & \cdot \\ & & \mathbf{D}_0 \end{bmatrix}$$

With these definitions, it is very easy to re-write the space-time kinetics equations of the preceding chapter in a much more compact form,

$$[\mathbf{v}]^{-1} \frac{\partial}{\partial t} [\phi] = \nabla \cdot [\mathbf{D}] \vec{\nabla} [\phi] - [\Sigma] [\phi] + (1 - \beta) [\chi^{p}] [\nu \Sigma_{f}]^{T} [\phi]$$

+
$$\sum_{i=1}^{D} [\chi_{i}^{d}] \lambda_{i} C_{i}$$
(EQ 20)
$$[\vec{J}] = -[D] \vec{\nabla} [\phi]$$

$$\frac{\partial}{\partial t} C_{i} = \beta_{i} [\nu \Sigma_{f}]^{T} [\phi] - \lambda_{i} C_{i}$$

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