Failure Data

Table B-1 Hazard Rates λ and Demand Failure Probabilities Q_d for Mechanical Hardware a,b

| Components | Failure mode | Assessed range on probability of occurrence | Computational median | Error factor |
|--|--|---|---------------------------------------|-----------------|
| 1. Pumps | | | · · · · · · · · · · · · · · · · · · · | |
| (includes | Failure to start on demand $Q_{\mathbf{d}}^{c}$ | $3 \times 10^{-4} - 3 \times 10^{-3} / d$ | 1 × 10 ⁻³ /d | 3 |
| driver) | Failure to run, given start λ_0 (normal environments) | $3 \times 10^{-6} - 3 \times 10^{-4}/hr$ | $3 \times 10^{-3}/hr$ | 10 |
| | Failure to run, given start λ_0 (extreme, post-accident environments inside containment) | $1 \times 10^{-4} - 1 \times 10^{-2}/hr$ | t × 10 ⁻³ /hr | 10 |
| | Failure to run, given start λ_0 (post- accident, after environmental recovery) | $3 \times 10^{-5} - 3 \times 10^{-3}/\text{hr}$ | 3 × 10 ⁻⁴ /hr | 10 |
| 2. Valves | | | | |
| a. Motor | Failure to operate (includes driver) Q_d^d | $3 \times 10^{-4} - 3 \times 10^{-3} / d$ | $1 \times 10^{-3}/d$ | 3 |
| operated: | Failure' to remain open (plug) Q_d | $3 \times 10^{-3} - 3 \times 10^{-4}/d$ | 1×10^{-4} | 3 |
| | λ _a | $1 \times 10^{-7} - 1 \times 10^{-6}/hr$ | $3 \times 10^{-7}/hr$ | 3 |
| | Rupture λ, | $1 \times 10^{-9} - 1 \times 10^{-7}/hr$ | $1 \times 10^{-n}/hr$ | 10 |
| b. Solenoid | Failure to operate Q_d | $3 \times 10^{-4} - 3 \times 10^{-3}$ /d | $1 \times 10^{-3}/d$ | 3 |
| operated: | Failure to remain open, Q_d (plug) | $3 \times 10^{-3} - 3 \times 10^{-4}$ | $1 \times 10^{-4}/d$ | 3 |
| | Rupture λ, | $1 \times 10^{-9} - 1 \times 10^{-7}/hr$ | 1 × 10 ⁻⁴ /hr | 10 |
| c. Air-fluid | Failure to operate Q_d | $1 \times 10^{-4} - 1 \times 10^{-3} / d$ | 3 × 10 ⁻⁴ /d | 3 |
| operated: | Failure to remain open Q_d (plug) | $3 \times 10^{-3} - 3 \times 10^{-4}$ /d | $1 \times 10^{-4}/d$ | 3 |
| | λ, | $1 \times 10^{-2} - 1 \times 10^{-6}/hr$ | $3 \times 10^{-7}/hr$ | 3 |
| | Rupture λ, | $1 \times 10^{-9} - 1 \times 10^{-7} / hr$ | ĭ × 10⁻*/hr | 10 |
| 3. Check valves | Failure to open Q_d | $3 \times 10^{-5} - 3 \times 10^{-4}/d$ | 1 × 10 ⁻⁴ /d | 3 |
| | Internal leak λ, (severe) | $1 \times 10^{-7} - 1 \times 10^{-6}/hr$ | $3 \times 10^{-7}/hr$ | 3 |
| | Rupture λ, | $1 \times 10^{-9} - 1 \times 10^{-7}/hr$ | 1 × 10 ^{-#} /ħr | 10 |
| 4. Vacuum valve | Failure to operate Q _d | $1 \times 10^{-5} - 1 \times 10^{-4} / d$ | 3×10^{-3} /d | 3 |
| Manual valve | Failure to remain open Q_d (plug) | $3 \times 10^{-5} - 3 \times 10^{-4}/d$ | $1 \times 10^{-4} / d$ | 3 |
| | Rupture λ, | $1 \times 10^{-9} - 1 \times 10^{-7}/hr$ | 1 × 10 ⁻⁸ /hr | 10 |
| Relief valves | Failure to open Q_d | $3 \times 10^{-6} - 3 \times 10^{-5} / d$ | $! \times 10^{-s}/d$ | 3 |
| | Premature open λ _e | $3 \times 10^{-6} - 3 \times 10^{-5}/\text{hr}$ | 1 × 10 ⁻⁸ /hr | 3 |
| 7. Test valves, flow meters, orifices | Failure to remain open Q_d (plug) | 1 × 10 ⁻⁴ -1 × 10 ⁻³ /d | 3 × 10⁻⁴/d | 3 |
| | Rupture λ, | $1 \times 10^{-9} - 1 \times 10^{-7}/hr$ | $1 \times 10^{-8}/hr$ | 10 |
| 8. Pipes | | | | |
| a. Pipe ≤ 7.5 cm diam per sec- tion | Rupture/plug λ _s , λ _e | 3 × 10 ⁻¹¹ -3 × 10 ⁻⁶ /hr | I × 10 ⁻⁹ /hr | 30 |

(Continued)

Table B-1 (Continued)

| Components | Failure mode | Assessed range on probability of occurrence | Computational median | Error factor |
|--|--------------------------|--|---------------------------|-----------------|
| b. Pipe > 7.5 cm diam per sec- tion | Rupture λ, λ, | $3 \times 10^{-12} - 3 \times 10^{-9} / \text{hr}$ | 1 × 10 ⁻¹⁰ /hr | 30 |
| Clutch, mechanical | Failure to operate Q_d | $1 \times 10^{-4} - 1 \times 10^{-3}/d$ | $3 \times 10^{-4}/d$ | 3 |
| 10. Scram rods (single) | Failure to insert | $3 \times 10^{-3} - 3 \times 10^{-4}/d$ | $1 \times 10^{-4}/d$ | 3 |

^a Frem Reactor Safety Study, Appendix III, Failure Data, WASH-1400, October 1975.

Table B-2 Hazard Rates λ and Demand Failure Probabilities Q_d for Electrical Equipment a,b

| Component | Failure mode | Assessed range | Computational median | Error factor |
|------------------------------------|--|--|--|-----------------|
| I. Clutch, electrical | Failure to operate Q_d^c | $1 \times 10^{-4} - 1 \times 10^{-3} / d$ | 3 × 10 ⁻⁴ /d | |
| | Premature disengagement Ao | $1 \times 10^{-7} - 1 \times 10^{-3}/hr$ | $1 \times 10^{-6}/\text{hr}$ | 3 |
| Motors, electric | Failure to start Qd | $1 \times 10^{-4} - 1 \times 10^{-3} / d$ | $3 \times 10^{-4}/d$ | 10 |
| | Failure to run, given start λ _e (normal environment) | $3 \times 10^{-6} - 3 \times 10^{-3}/hr$ | 1 × 10 ⁻³ /hr | 3 |
| | Failure to run, given start λ ₀ (extreme environment) | $1 \times 10^{-4} - 1 \times 10^{-2}/hr$ | 1 × 10 ⁻³ /hr | 01 |
| 3. Relays | Failure to energize Q_d | $3 \times 10^{-5} - 3 \times 10^{-4} / d$ | l × 10⁻⁴/d | • |
| | Failure of NO contacts to close, given energized λ_a | $1 \times 10^{-7} - 1 \times 10^{-6}/hr$ | $3 \times 10^{-7}/hr$ | 3 |
| | Failure of NC contacts by opening, given not energized λ_0 | $3 \times 10^{-8} - 3 \times 10^{-7}/hr$ | I × 10 ⁻⁷ /hr | 3 |
| | Short across NO/NC contact \(\lambda_6\) | $1 \times 10^{-9} - 1 \times 10^{-7} / hr$ | 1 × 10 ⁻⁸ /hr | 10 |
| | Coil open A ₀ | $1 \times 10^{-8} - 1 \times 10^{-6}/hr$ | 1 × 10 -7/hr | 10 |
| | Coil short to power A. | $1 \times 10^{-9} - 1 \times 10^{-7} / hr$ | I × 10 7111 | 10 |
| 4. Circuit breakers | Failure to transfer Q. | $3 \times 10^{-4} - 3 \times 10^{-3} / d$ | 1 × 10 -3/d | 3 |
| | Premature transfer A. | $3 \times 10^{-7} - 3 \times 10^{-6}/hr$ | l × 10 - 1/hr | 3 |
| 5. Switches | • | 5 14 - 5 × 10 /m | i x io 7nr | , |
| a. Limit | Failure to operate Q2 | $1 \times 10^{-4} - 1 \times 10^{-3} / d$ | 3 × 10 ⁻⁴ /d | 3 |
| b. Torque | Failure to operate Q | 3 × 10 ⁻⁴ – 3 × 10 ⁻⁴ /d | • | 3 |
| c. Pressure | Failure to operate Q4 | $3 \times 10^{-5} - 3 \times 10^{-4}/d$ | 1 × 10 ⁻⁴ /d 1 × 10 ⁻⁴ /d | 3 |
| d. Manual | Failure to transfer Q | $3 \times 10^{-4} - 3 \times 10^{-3} / d$ | 1 × 10 - 5/d | 3 |

^aSee Section 5-3 for discussion of use.

Demand probabilities are based on the presence of proper input control signals. For turbine driven pumps, the effect of failures of valves, sensors, and other auxiliary hardware may result in significantly higher overall failure rates for turbine driven pump systems.

Demand probabilities are based on presence of proper input control signals.

Plug probabilities are given in demand probability, and per hour rates, since phenomena are generally time dependent, but plugged condition may only be detected upon a demand of the system.

Table B-2 (Continued)

| Component | Failure mode | Assessed range | Computational median | Error factor |
|---|--|---|--------------------------|-----------------|
| 6. Switch contacts | Failure of NO contacts to close given switch operation λ_0 | $1 \times 10^{-8} - 1 \times 10^{-c}/hr$ | I × 10 ⁻⁷ /hr | 10 |
| | Failure of NC by opening, given no switch operation λ_0 | $3 \times 10^{-9} - 3 \times 10^{-7} / \text{hr}$ | $3 \times 10^{-4}/hr$ | 10 |
| | Short across NO/NC contact A ₀ | $1 \times 10^{-9} - 1 \times 10^{-7}/hr$ | 1 × 10~*/hr | 10 |
| 7. Battery power systems (wet cell) | Failure to provide proper output λ_s | $1 \times 10^{-6} - 1 \times 10^{-5}/\text{hr}$ | 3 × 10 ⁻⁶ /hr | 3 |
| 8. Transformers | Open circuit primary or secondary \(\lambda_0\) | $3 \times 10^{-7} - 3 \times 10^{-6} / hr$ | l × 10 ⁻⁶ /hr | 3 - |
| | Short primary to secondary λ ₀ | $3 \times 10^{-7} - 3 \times 10^{-6}/hr$ | 1 × 10 ⁻⁶ /hr | 3 |
| 9a. Solid state devices hi power applica- tions (diodes, transistors, etc.) | Fails to function λ ₀ | $3 \times 10^{-7} - 3 \times 10^{-3} / \text{hr}$ | 3 × 10 ⁻⁶ /hr | 10 |
| | Fails shorted A ₀ | $1 \times 10^{-7} - 1 \times 10^{-3} / hr$ | $1 \times 10^{-6}/hr$ | 10 |
| b. Solid state devices, low power applications | Fails to function λ ₀ | 1 × 10 ⁻⁷ -1 × 10 ⁻³ /hr | 1 × 10 ⁻⁶ /hr | 10 |
| | Fails shorted | $1 \times 10^{-\kappa} - 1 \times 10^{-6}/hr$ | 1 × 10 ⁻¹ /hr | 10 |
| 10a. Diesels (com- plete plant) | Failure to start Q_d | $1 \times 10^{-2} - 1 \times 10^{-1} / d$ | 3×10^{-2} /d | 3 |
| | Failure to run, emergency conditions, given start λ_0 | $3 \times 10^{-4} - 3 \times 10^{-2}/\text{hr}$ | 3 × 10 ⁻³ /hr | 10 |
| b. Diesels (engine only) | Failure to run, emergency conditions, given start λ_0 | $3 \times 10^{-3} - 3 \times 10^{-3}/hr$ | 3 × 19 ⁻⁴ /hr | 10 |
| 11. Instrumen- tation—general (includes trans- mitter, amplifier, and output device) | Failure to operate λ ₀ | 1 × 10 ⁻⁷ -[× 10 ⁻³ /hr | 1 × 10 */hr | 10 |
| | Shift in calibration λ_0 | $3 \times 10^{-6} - 3 \times 10^{-4}/hr$ | $3 \times 10^{-3}/hr$ | 10 |
| 12. Fuses | Failure to open Q_d | $3 \times 10^{-6} - 3 \times 10^{-3} / d$ | $1 \times 10^{-3}/d$ | 3 |
| | Premature open λ ₀ | $3 \times 10^{-7} - 3 \times 10^{-6}/\text{hr}$ | $1 \times 10^{-6}/hr$ | 3 |
| 13. Wires (typical circuits, several joints) | Open circuit λ ₀ | I × 10 ⁻⁶ –I × 10 ⁻⁵ /hr | 3 × 10 ⁻⁶ /hr | 3 |
| | Short, to ground λ_0 | $3 \times 10^{-6} - 3 \times 10^{-6} / \text{hr}$ | $3 \times 10^{-7}/hr$ | 10 |
| | Short to power A ₀ | $1 \times 10^{-9} - 1 \times 10^{-7}/hr$ | 1 × 10 ⁻ "/hr | 10 |
| 14. Terminal boards | Open connection λ_0 | $1 \times 10^{-8} - 1 \times 10^{-6}/hr$ | l × 10 ^{-†} /hr | 10 |
| | Short to adjacent circuit Ag | I × 10 ⁻⁹ ~I × 10 ⁻⁷ /hr | 1 × 10 ^{-*} /hr | 10 |

^a From Reactor Safety Study, Appendix III, Failure Data, WASH-1400, October 1975.

^{*} See Section 5-3 for discussion of use.

^e Demand probabilities are based on presence of proper input control signals.

Table B-3 Human Error Probabilities a.b

| Demand failure probability | Activity |
|----------------------------------|--|
| 10-4 | Selection of a key-operated switch rather than a nonkey switch. (This value does not include the error of decision where the operator misinterprets situation and believes key switch is correct choice.) |
| 10-3 | desired switch (or pair of switches) dissimilar in shape or location to the |
| 3×10^{-3} | General human error of commission, e.g., misreading label and therefore |
| 10-2 | selecting wrong switch. General human error of omission when there is no display in the control room of the status of the item omitted, e.g., failure to return manually operated test valve to proper configuration after maintenance. |
| 3×10^{-3} | rather than at the end as above |
| 3 × 10 ⁻² | Simple arithmetic errors with self-checking but without repeating the calculation by redoing it on another piece of paper |
| 1/x | Given that an operator is reaching for an incorrect switch (or pair of switches), he or she selects a particular similar appearing switch (or pair of switches), where $x = $ the number of incorrect switches (or pairs of switches) adjacent to the desired switch (or pair of switches). The $1/x$ applies up to 5 or 6 items. After that point the error rate would be lower because the operator would take more time to search. With up to 5 or 6 items, the operator doesn't expect to be wrong and therefore is more likely to do less deliberate searching. |
| 0-1 | Given that an operator is reaching for a wrong motor operated valve MOV switch (or pair of switches), he or she fails to note from the indicator lamps that the MOV(s) is (are) already in the desired state and merely changes the status of the MOV(s) without recognizing that he or she had selected the wrong switch(es). |
| 1.0 | Same as above, except that the state(s) of the incorrect switch(es) is (are) not the desired state. |
| 1.0 | If an operator fails to operate correctly one of two closely coupled valves or switches in a procedural step, he or she also fails to correctly operate the other valve. |
|)-1 | Monitor or inspector fails to recognize initial error by operator. Note: With continuing feedback of the error on the annunciator panel, this high error rate would not apply. |
|)-1 | Personnel on different work shift fail to check condition of hardware unless required by checklist or written directive. |

Table B-3 (Continued)

| Demand failure probability | Activity |
|----------------------------------|--|
| 5 × 10 ⁻¹ | Monitor fails to detect undesired position of valves, etc., during general walk- around inspections, assuming no check list is used. |
| 0.2-0.3 | General error rate, given very high stress levels, where dangerous activities are occurring rapidly |
| 2 ⁽ⁿ⁻¹⁾ x | Given severe time stress, as in trying to compensate for an error made in an emergency situation, the initial error rate x , for an activity doubles for each attempt, n , after a previous incorrect attempt, until the limiting condition of an error rate of 1.0 is reached or until time runs out. This limiting condition corresponds to an individual's becoming completely disorganized or ineffective. |
| ~1.0 | Operator fails to act correctly in the first 60 seconds after the enset of an extremely high stress condition, e.g., a large LOCA. |
| 9 × 10 ⁻¹ | Operator fails to act correctly after the first 5 minutes after the onset of an extremely high stress condition. |
| 10-1 | Operator fails to act correctly after the first 30 minutes in an extreme stress condition. |
| 10-2 | Operator fails to act correctly after the first several hours in a high stress condition. |
| <i>x</i> | After 7 days after a large LOCA, there is a complete recovery to the normal error rate x , for any task. |

^a Reactor Safety Study, Appendix III, Failure Data, WASH-1400 (October 1975).

^b See Section 5-4 for discussion of use.